

P.O. Box 181915 • Dallas, TX 75218 • Tel 972.840.0208 • Fax 972.840.1046

Configuring a PushCorp FCU Flex with EIP

Required PushCorp Components:

FCU Flex PAR04288 – FCU Flex EIP Module

Required Software:

HMS AnyBus Ethernet IP Tool

Download: https://www.anybus.com/docs/librariesprovider7/default-document-library/ software/hms-ipconfigtool.zip?sfvrsn=ff5b9ad6_60

PushCorp AFD Dashboard

Download: https://cloud.pushcorp.com/webdata/software/afddashboard.msi

Instructions:

- 1. Use HMS Anybus Ethernet IP Tool to set the IP address on the FCU Flex EIP Moudule.
- 2. Once the IP has been set, reboot the FCU Flex by cycling power.
- 3. Open the AFD Dashboard software and navigate to the IO screen by way of the settings icon.
- 4. Verify that the IP address shown here matches the IP address entered in HMS Config Tool.
- 5. The FCU is now ready to communicate with the scanner of your choice.

Configuring your adapter to communicate with the FCU Flex

Allen Bradley PLC

- 1. Right click on the PLC Ethernet card in the IO Tree
- 2. Select "New Module"





P.O. Box 181915 • Dallas, TX 75218 • Tel 972.840.0208 • Fax 972.840.1046

3. From the "Select Module Type" pop up window Search for and Select "Generic Ethernet Module"

generi		C	lear f	ilters		Hide Filters	*
	Module Type Category	/ Filters	*		Module Type Ven	dor Filters	*
Analog CIP Motion Co Communication Communication	nverter 1 15 Adapter			Advance Cognex Cognex Endress FANUC	ed Energy Industries, In Corporation +Hauser CORPORATION	с.	
•		•		•	m		F
Catalog Number	1	Description	Ven	dor	Category		
ETHERNET-BR	IDGE (Generic EtherNe	Roc	kwell Autom	Communication		
ETHERNET-MC	DULE (Generic Etherne	Roc	kwell Autom	Communication		
ETHERNET-SA	FETYMODULE	Seneric EtherNe	Roc	kwell Autom	Safety,Other		
2 of FE1 Module Tree	a Found					Add to Fave	viter

4. Press Create, then the new module window will appear and you can enter the Name of the Module, IP address, and the connection parameters as shown in the screen shot. Note: Configuration = 1, 0 (8-bit)

Type: ETHERN Vendor: Rockwel Parent: ENBT_0	NET-MODULE Generic Ether I Automation/Allen-Bradley 2	net Module			
Name: PushCor Description:	p_R1	Connection Para	Assembly Instance: 100	Size:	
Comm Format: Data - II Address / Host Name IP Address: 19 Host Name:	NT •	Status Output: Status Input: Status Output:		0	v (10 bit)

Note: Input and Output should be set to 16-bit

Fanuc Robot

- 1. Setup the EIP interface on the FANUC robot, this will be done on "Rack 89".
- 2. The FCU will be setup as scanner
- 3. The FANUC robot does not use the standard Maj and Min revisions which would be found in the EDS file, replace the settings for Maj and Min revisions shown below with 0.



P.O. Box 181915 • Dallas, TX 75218 • Tel 972.840.0208 • Fax 972.840.1046



General	may .
I/O Data Type :	16-BIT WORDS
Timeout Multiplier	:4
Reconnect :	FALSE
Major Revision :	0
Minor Revision :	0
Alarm Severity :	omon
Quick Connect .	Paren
Originator To Target	LADOR
RPT -	
Target To Opigiasto	25
Transport m.	
ppr :	UNICAST
RPI :	25
connection Type	
TAbe :	
O=>T Format :	Run/Idle Header
T=>0 Format :	Modeless
Configuration String St	tatue
Cine /buch and	0
2 (Z H [P107 G P] +	14

4. Once the settings have been you can set the device to true and finish your standard Fanuc interface configuration.

Note: If there is an active PING but the connection continues to stay "Pending", the "Configuration Instance" may be incorrect.

EIP Configuration Parameters

VendCode = 1444; ProdType = 43; ProdCode = 55; MajRev = 1; MinRev = 1; Producing Connection (Input): 100 Consuming Connection (Output): 150 Input Scanner Size: 10 Words Input Offset: 0 Output Scanner Size: 5 Words Output Offset: 0